

Communication Networks

Prof. Laurent Vanbever

Communication Networks

Spring 2022



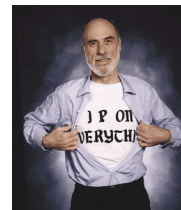
Laurent Vanbever
nsg.ee.ethz.ch

ETH Zürich (D-ITET)
March 28 2022

Materials inspired from Scott Shenker & Jennifer Rexford

Last week on
Communication Networks

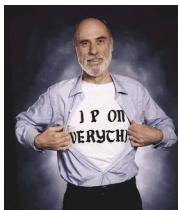
Internet Protocol and Forwarding



source: Boardwatch Magazine

- 1 IP addresses
use, structure, allocation
- 2 IP forwarding
longest prefix match rule
- 3 IP header
IPv4 and IPv6, wire format

Internet Protocol and Forwarding

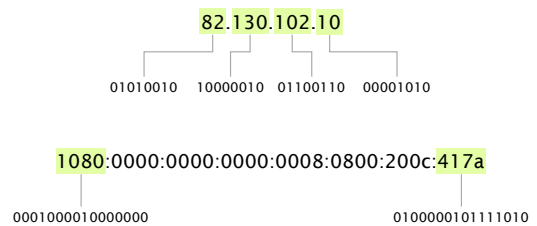


- 1 IP addresses
use, structure, allocation

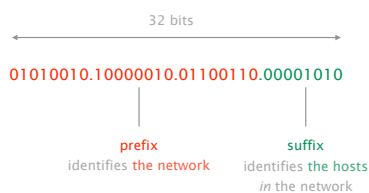
IP forwarding
longest prefix match rule

IP header
IPv4 and IPv6, wire format

IP addresses are unique 32/128-bits number
associated to a network interface (on a host, a router, ...)

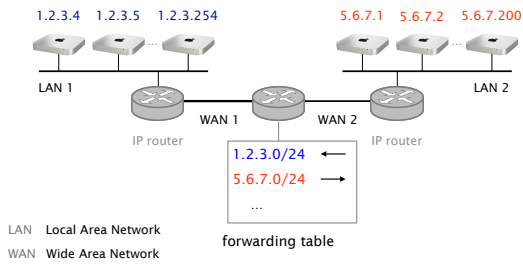


IP addressing is hierarchical, composed of
a prefix (network address) and a suffix (host address)



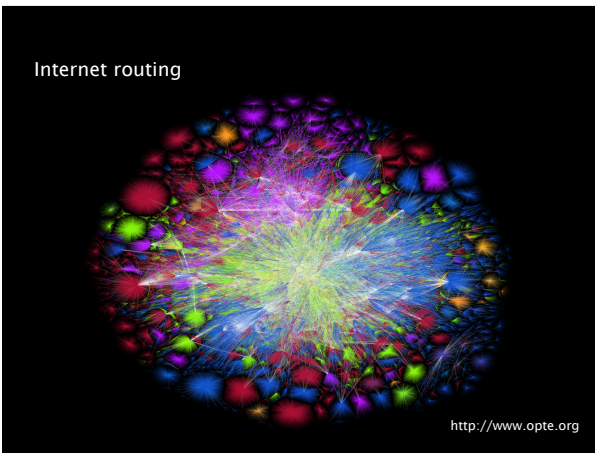
Routers forward packet to their destination
according to the network part, *not* the host part

Doing so enables to scale the forwarding tables



This week on
Communication Networks

Internet routing



Internet routing comes into two flavors:
intra- and *inter-domain* routing

inter-domain
routing

Find paths *between* networks

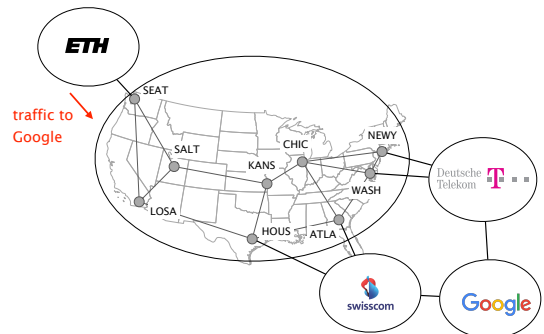
intra-domain
routing

Find paths *within* a network

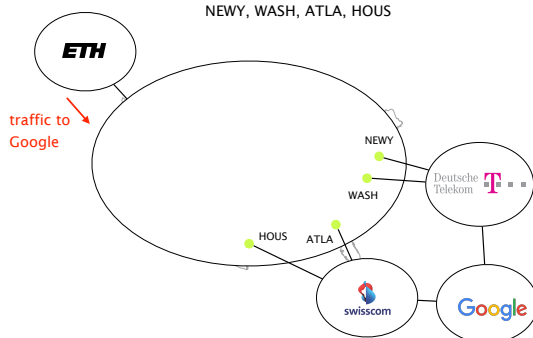
inter-domain
routing

Find paths *between* networks

intra-domain
routing



Google can be reached via
NEWY, WASH, ATLA, HOUS



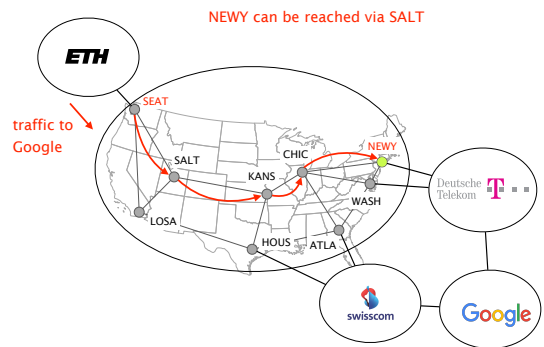
Google can be reached via
NEWY, WASH, ATLA, HOUS

best exit point
based on money, performance, ...

inter-domain routing

intra-domain routing

Find paths **within** a network



> traceroute www.google.ch

```

rou-etx-1-ee-tik-etx-dock-1
rou-ref-rz-bb-ref-rz-etx
rou-fw-rz-ee-tik
rou-fw-rz-gw-rz
swiix1-10ge-1-4.switch.ch
swiez2
swiix2-p1.switch.ch
equinix-zurich.net.google.com
66.249.94.157
zrh04s06-in-f24.1e100.net

```

intra-domain routing

intra-domain routing

intra-domain routing

> traceroute www.google.ch

```

rou-etx-1-ee-tik-etx-dock-1
rou-ref-rz-bb-ref-rz-etx
rou-fw-rz-ee-tik
rou-fw-rz-gw-rz
swiix1-10ge-1-4.switch.ch
swiez2
swiix2-p1.switch.ch
equinix-zurich.net.google.com
66.249.94.157
zrh04s06-in-f24.1e100.net

```

inter-domain routing

inter-domain routing

Internet routing

from here to there, and back



- Intra-domain routing**
Link-state protocols
Distance-vector protocols
- Inter-domain routing**
Path-vector protocols

Internet routing

from here to there, and back



- Intra-domain routing**
Link-state protocols
Distance-vector protocols
- Inter-domain routing**
Path-vector protocols

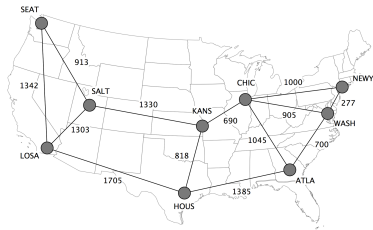
Intra-domain routing enables routers to compute **forwarding paths** to any internal subnet

what kind of paths?

Network operators don't want arbitrary paths, they want **good paths**

- definition A good path is a path that minimizes some network-wide metric
typically delay, load, loss, cost
- approach Assign to each link a weight (usually static), compute the *shortest-path* to each destination

When weights are assigned **proportionally** to the distance, shortest-paths will minimize the end-to-end delay



Internet2, the US-based research network

When weights are assigned proportionally to the distance, shortest-paths will **minimize the end-to-end delay**

if traffic is such that there is no congestion

When weights are assigned **inversely proportionally** to each link capacity, **throughput is maximized**

if traffic is such that there is no congestion

Internet routing

from here to there, and back



- 1 Intra-domain routing
 - Link-state protocols
 - Distance-vector protocols
- Inter-domain routing
 - Path-vector protocols

In Link-State routing, routers build a precise map of the network by flooding local views to everyone

Each router keeps track of its incident links and cost as well as whether it is up or down

Each router broadcast its own links state to give every router a complete view of the graph

Routers run Dijkstra on the corresponding graph to compute their shortest-paths and forwarding tables

Flooding is performed as in L2 learning

Node sends its link-state on all its links

Next node does the same, except on the link where the information arrived

Flooding is performed as in L2 learning **except that it is reliable**

Node sends its link-state on all its links

Next node does the same, except on the link where the information arrived

All nodes are **ensured** to receive the **latest version** of all link-states

challenges
packet loss
out of order arrival

Flooding is performed as in L2 learning **except that it is reliable**

Node sends its link-state on all its links

Next node does the same, except on the link where the information arrived

All nodes are **ensured** to receive the **latest version** of all link-states

solutions

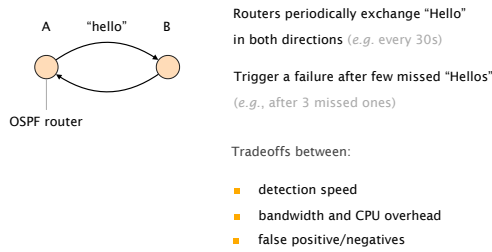
ACK & retransmissions
sequence number
time-to-live for each link-state

A link-state node initiate flooding in 3 conditions

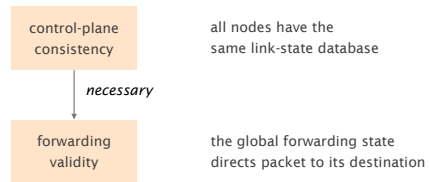
Topology change	link or node failure/recovery
Configuration change	link cost change
Periodically	refresh the link-state information every (say) 30 minutes account for possible data corruption

Once a node knows the entire topology, it can compute shortest-paths using Dijkstra's algorithm

By default, Link-State protocols detect topology changes using software-based beaconing

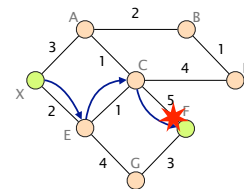


During network changes, the link-state database of each node might differ



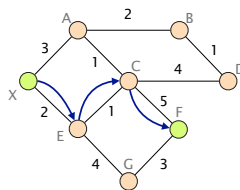
Inconsistencies lead to transient disruptions in the form of blackholes or forwarding loops

Blackholes appear due to detection delay, as nodes do not immediately detect failure

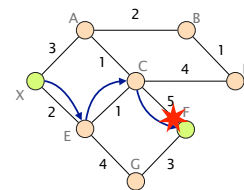


depends on the timeout for detecting lost hellos

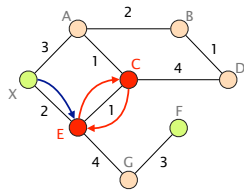
Transient loops appear due to inconsistent link-state databases



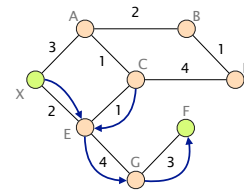
Initial forwarding state



C learns about the failure and immediately reroute to E



A loop appears as E isn't yet aware of the failure



The loop disappears as soon as E updates its forwarding table

Convergence is the process during which the routers seek to actively regain a consistent view of the network

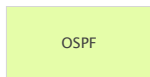
Today, two Link-State protocols are widely used: OSPF and IS-IS



Open Shortest Path First

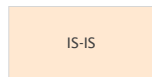


Intermediate Systems²



Open Shortest Path First

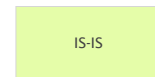
used in many enterprise & ISPs
work on top of IP
only route IPv4 by default



Intermediate Systems²



Open Shortest Path First



Intermediate Systems²

used mostly in large ISPs
work on top of link-layer
network protocol agnostic

Internet routing
from here to there, and back



- 1 Intra-domain routing
 - Link-state protocols
 - Distance-vector protocols

- Inter-domain routing
 - Path-vector protocols

Distance-vector protocols are based on Bellman-Ford algorithm

Let $d_x(y)$ be the cost of the least-cost path known by x to reach y

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Each node bundles these distances into one message (called a vector) that it repeatedly sends to all its neighbors

until convergence

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Each node bundles these distances into one message (called a vector) that it repeatedly sends to all its neighbors

until convergence

Each node updates its distances based on neighbors' vectors:

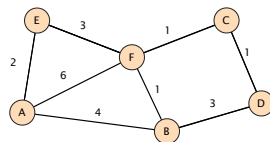
$$d_x(y) = \min\{c(x,v) + d_v(y)\} \text{ over all neighbors } v$$

Similarly to Link-State, 3 situations cause nodes to send new DVs

Topology change link or node failure/recovery

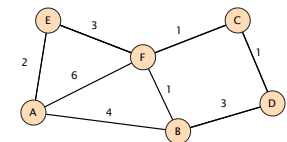
Configuration change link cost change

Periodically refresh the link-state information every (say) 30 minutes account for possible data corruption



Optimum 1-hop path

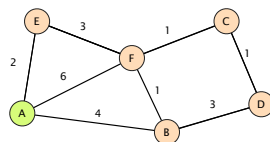
A			B		
Dst	Cst	Hop	Dst	Cst	Hop
A	0	A	A	4	A
B	4	B	B	0	B
C	∞	-	C	∞	-
D	∞	-	D	3	D
E	2	E	E	∞	-
F	6	F	F	1	F



C			D			E			F		
Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop
A	∞	-	A	∞	-	A	2	A	A	6	A
B	∞	-	B	3	B	B	∞	-	B	1	B
C	0	C	C	1	C	C	∞	-	C	1	C
D	1	D	D	0	D	D	∞	-	D	∞	-
E	∞	-	E	∞	-	E	0	E	E	3	E
F	1	F	F	∞	-	F	3	F	F	0	F

Optimum 1-hop path

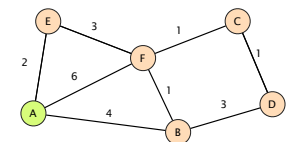
A			B		
Dst	Cst	Hop	Dst	Cst	Hop
A	0	A	A	4	A
B	4	B	B	0	B
C	∞	-	C	∞	-
D	∞	-	D	3	D
E	2	E	E	∞	-
F	6	F	F	1	F



C			D			E			F		
Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop
A	∞	-	A	∞	-	A	2	A	A	6	A
B	∞	-	B	3	B	B	∞	-	B	1	B
C	0	C	C	1	C	C	∞	-	C	1	C
D	1	D	D	0	D	D	∞	-	D	∞	-
E	∞	-	E	∞	-	E	0	E	E	3	E
F	1	F	F	∞	-	F	3	F	F	0	F

Optimum 2-hops path

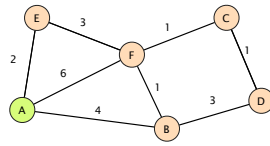
A			B		
Dst	Cst	Hop	Dst	Cst	Hop
A	0	A	A	4	A
B	4	B	B	0	B
C	7	F	C	2	F
D	7	B	D	3	D
E	2	E	E	4	F
F	5	E	F	1	F



C			D			E			F		
Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop
A	7	F	A	7	B	A	2	A	A	5	B
B	2	F	B	3	B	B	4	F	B	1	B
C	0	C	C	1	C	C	4	F	C	1	C
D	1	D	D	0	D	D	∞	-	D	2	C
E	4	F	E	∞	-	E	0	E	E	3	E
F	1	F	F	2	C	F	3	F	F	0	F

Optimum 3-hops path

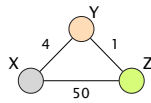
A			B		
Dst	Cst	Hop	Dst	Cst	Hop
A	0	A	A	4	A
B	4	B	B	0	B
C	6	E	C	2	F
D	7	F	D	3	D
E	2	E	E	4	F
F	5	E	F	1	F



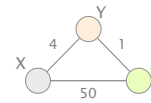
C			D			E			F		
Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop	Dst	Cst	Hop
A	6	F	A	7	B	A	2	A	A	5	B
B	2	F	B	3	B	B	4	F	B	1	B
C	0	C	C	1	C	C	4	F	C	1	C
D	1	D	D	0	D	D	5	F	D	2	C
E	4	F	E	5	C	E	0	E	E	3	E
F	1	F	F	2	C	F	3	F	F	0	F

Let's consider the convergence process after a link cost change

Consider the following network



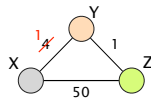
Consider the following network leading to the following vectors



Y vector
 dest. via X Z — Y reaches X directly
 X 4 6

Z vector
 dest. via X Y — Z reaches X via Y
 X 50 5

t = 0
 (X,Y) weight changes from 4 to 1



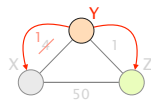
time t=0

Y vector
 dest. via X Z
 X 4 6

Z vector
 dest. via X Y
 X 50 5

Node detects local cost change, update their vectors, and notify their neighbors if it has changed

t = 1
 Y updates its vector, sends it to X and Z

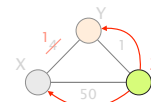


t=0 t=1

Y vector
 dest. via X Z dest. via X Z
 X 4 6 X 1 6

Z vector
 dest. via X Y
 X 50 5

t = 2
 Z updates its vector, sends it to X and Y

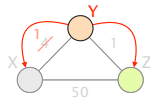


t=0 t=1 t=2

Y vector
 dest. via X Z dest. via X Z
 X 4 6 X 1 6

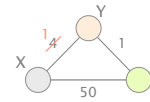
Z vector
 dest. via X Y dest. via X Y
 X 50 5 X 50 2

t = 3
Y updates its vector,
sends it to X and Z



	t=0	t=1	t=2	t=3
Y vector	dest. via X Z	dest. via X Z		dest. via X Z
	X 4 6	X 1 6		X 1 3
Z vector	dest. via X Y		dest. via X Y	
	X 50 5		X 50 2	

t > 3
no one moves anymore
network has converged!



	t=0	t=1	t=2	t > 3
Y vector	dest. via X Z	dest. via X Z		dest. via X Z
	X 4 6	X 1 6		X 1 3
Z vector	dest. via X Y		dest. via X Y	dest. via X Y
	X 50 5		X 50 2	X 50 2

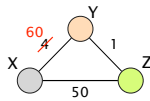
The algorithm terminates
after 3 iterations

Good news travel fast!

Good news travel fast!

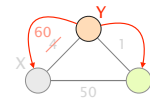
What about bad ones?

t = 0
(X,Y) weight changes
from 4 to 60



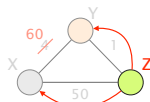
time	t=0
Y vector	dest. via X Z
	X 4 6
Z vector	dest. via X Y
	X 50 5

t = 1
Y updates its vector,
sends it to X and Z



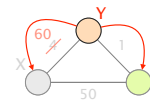
	t=0	t=1
Y vector	dest. via X Z	dest. via X Z
	X 4 6	X 60 6
Z vector	dest. via X Y	
	X 50 5	

t = 2
Z updates its vector,
sends it to X and Y



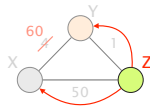
	t=0	t=1	t=2
Y vector	dest. via X Z	dest. via X Z	
	X 4 6	X 60 6	
Z vector	dest. via X Y		dest. via X Y
	X 50 5		X 50 7

t = 3
Y updates its vector,
sends it to X and Z



	t=0	t=1	t=2	t=3
Y vector	dest. via X Z	dest. via X Z		dest. via X Z
	X 4 6	X 60 6		X 60 8
Z vector	dest. via X Y		dest. via X Y	
	X 50 5		X 50 7	

t = 4
Z updates its vector,
sends it to X and Y...



t=4
Y vector
X 50 9
Z vector
dest. via X Y
X 50 9

t=4
Y vector
X 50 9
... many iterations later ...
t=44
dest. via X Z
X 60 51
dest. via X Y
X 50 52

The algorithm terminates
after 44 iterations!

Bad news travel slow!

This problem is known as
count-to-infinity, a type of routing loop

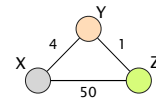
Count-to-infinity leads to very slow convergence
what if the cost had changed from 4 to 9999?

Routers don't know when neighbors use them
Z does not know that Y has switched to use itself

Let's try to fix that

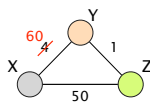
Whenever a router uses another one,
it will announce it an infinite cost

The technique is known as poisoned reverse



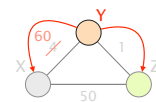
Y vector
dest. via X Z
X 4 ∞
Z vector
dest. via X Y
X 50 5
As Z uses Y to reach X,
it announces to Y an infinite cost

t = 0
(X,Y) weight changes
from 4 to 60



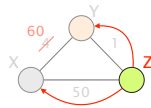
time t=0
Y vector
dest. via X Z
X 4 ∞
Z vector
dest. via X Y
X 50 5

t = 1
Y updates its vector,
sends it to X and Z



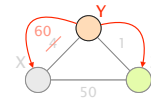
t=0
Y vector
dest. via X Z
X 4 ∞
Z vector
dest. via X Y
X 50 5
t=1
Y vector
dest. via X Z
X 60 ∞
Z vector
dest. via X Y
X 50 5

t = 2
Z updates its vector,
sends it to X and Y



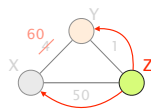
	t=0	t=1	t=2
Y vector	dest. via X Z	dest. via X Z	
	X 4 ∞	X 60 ∞	
Z vector	dest. via X Y		dest. via X Y
	X 50 5		X 50 61

t = 3
Y updates its vector,
sends it to X and Z



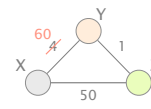
	t=0	t=1	t=2	t=3
Y vector	dest. via X Z	dest. via X Z		dest. via X Z
	X 4 ∞	X 60 ∞		X 60 51
Z vector	dest. via X Y		dest. via X Y	
	X 50 5		X 50 61	

t = 4
Z updates its vector,
sends it to X and Y



	t=4
Y vector	
Z vector	dest. via X Y
	X 50 ∞

t > 4
no one moves
network has converged!



	t=4	t > 4
Y vector		dest. via X Z
		X 60 51
Z vector	dest. via X Y	dest. via X Y
	X 50 ∞	X 50 ∞

While poisoned reverse solved this case,
it does **not** solve loops involving 3 or more nodes...

see exercise session

Actual distance-vector protocols mitigate
this issue by using small "infinity", e.g. 16

Link-State vs Distance-Vector routing

	Message complexity	Convergence speed	Robustness
Link-State	O(nE) message sent n: #nodes E: #links	relatively fast	node can advertise incorrect link cost nodes compute their own table
Distance-Vector	between neighbors only	slow	node can advertise incorrect path cost errors propagate

Internet routing from here to there, and back



Intra-domain routing
Link-state protocols
Distance-vector protocols

2 Inter-domain routing
Path-vector protocols

Internet

Internet

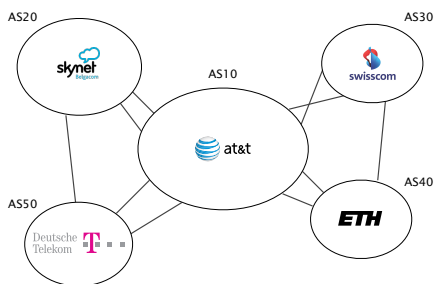
Internet

A network of networks

Internet

Border Gateway Protocol (BGP)

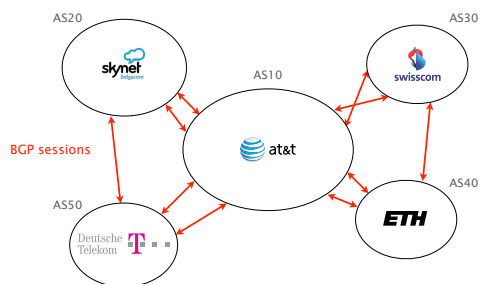
The Internet is a network of networks, referred to as Autonomous Systems (AS)



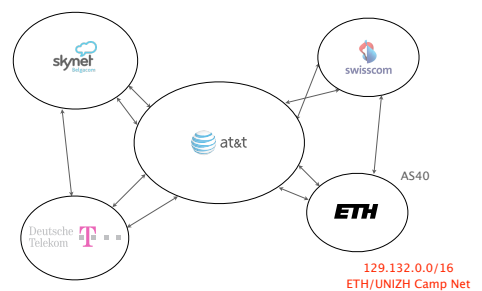
Each AS has a number (encoded on 16 bits) which identifies it



BGP is the routing protocol "glueing" the entire Internet together



Using BGP, ASes exchange information about the IP prefixes they can reach, directly or indirectly



BGP needs to solve three key challenges:
scalability, privacy and policy enforcement

There is a huge # of networks and prefixes
1M prefixes, >70,000 networks, millions (!) of routers

Networks don't want to divulge internal topologies
or their business relationships

Networks need to control where to send and receive traffic
without an Internet-wide notion of a link cost metric

Link-State routing **does not** solve
these challenges

Floods topology information
high processing overhead

Requires each node to compute the entire path
high processing overhead

Minimizes some notion of total distance
works only if the policy is shared and uniform

Distance-Vector routing is on the right track

pros Hide details of the network topology
nodes determine only "next-hop" for each destination

Distance-Vector routing is on the right track,
but not really there yet...

pros Hide details of the network topology
nodes determine only "next-hop" for each destination

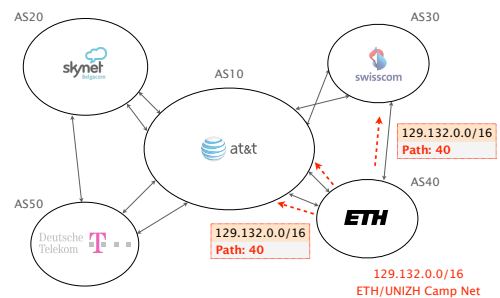
cons It still minimizes some common distance
impossible to achieve in an inter domain setting

It converges slowly
counting-to-infinity problem

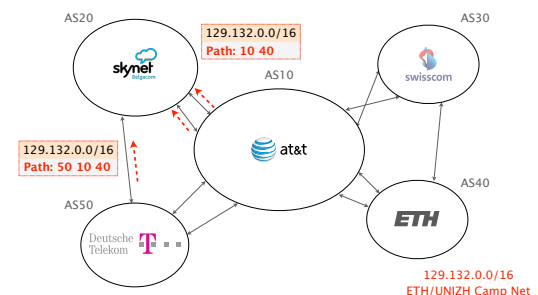
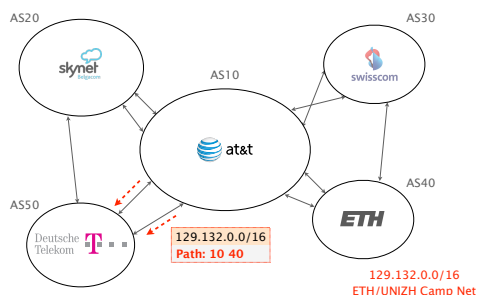
BGP relies on **path-vector routing** to support
flexible routing policies and avoid count-to-infinity

key idea advertise the **entire path** instead of distances

BGP announcements carry complete path information
instead of distances

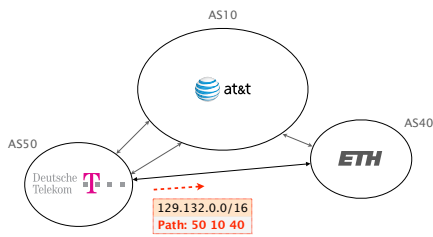


Each AS appends itself to the path
when it propagates announcements



Complete path information enables ASes to easily detect a loop

ETH sees itself in the path and discard the route



Life of a BGP router is made of three consecutive steps

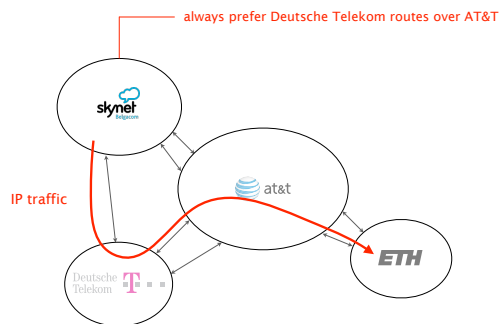
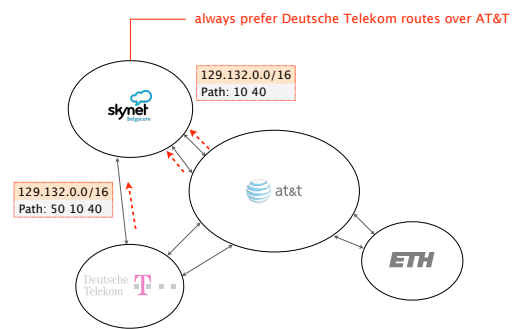
while true:

- receives routes from my neighbors
- select one best route for each prefix
- export the best route to my neighbors

Each AS can apply local routing policies

Each AS is free to

- select and use any path preferably, the cheapest one



Each AS can apply local routing policies

Each AS is free to

- select and use any path preferably, the cheapest one
- decide which path to export (if any) to which neighbor preferably, none to minimize carried traffic

