Communication Networks

Prof. Laurent Vanbever



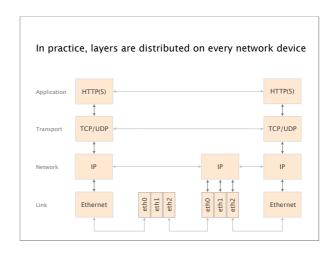
Last week on Communication Networks

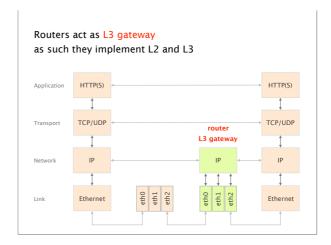
Communication Networks Part 1: General overview #1 What is a network made of? #2 How is it shared? #3 How is it organized? #4 How does communication happen? #5 How do we characterize it?

Communication Networks Part 1: General overview What is a network made of? How is it shared? How is it organized? #4 How does communication happen? How do we characterize it?

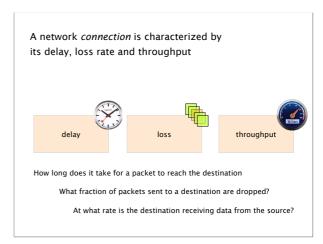
	dependent layers (or 7 layers for the OSI model)
	layer
L	Application
L	Transport
L	Network
L	Link
L	Physical

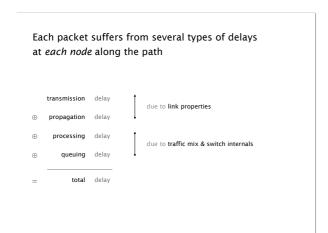
Each layer provides a service to the layer above layer service provided: L5 Application network access L4 Transport end-to-end delivery (reliable or not) L3 Network global best-effort delivery L2 Link local best-effort delivery L1 Physical physical transfer of bits

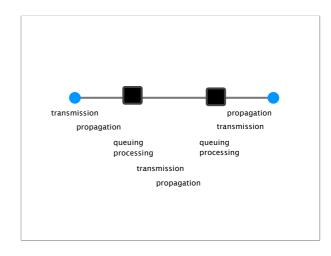








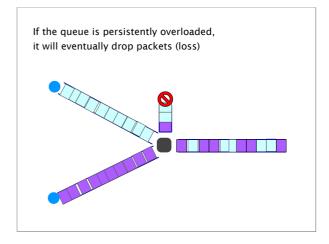


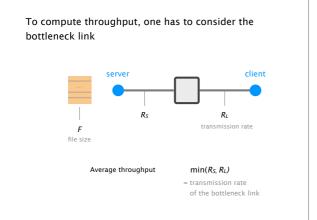


The queuing delay is the amount of time a packet waits (in a buffer) to be transmitted on a link

Queuing delay is the hardest to evaluate as it varies from packet to packet

It is characterized with statistical measures e.g., average delay & variance, probability of exceeding x

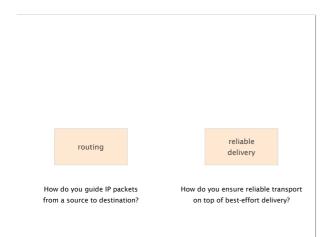


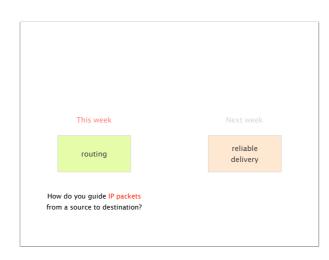


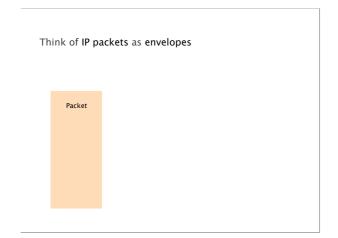


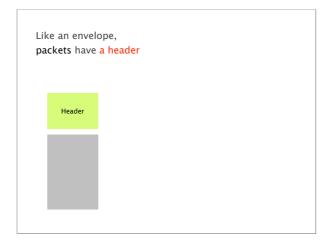


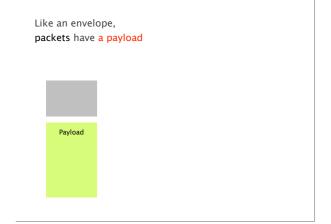


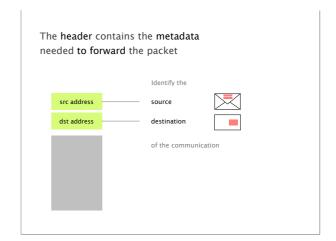


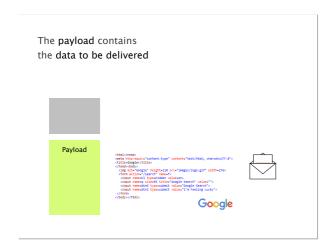




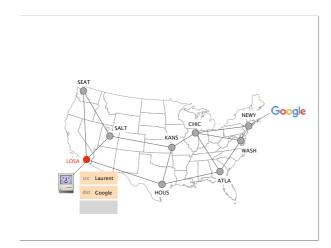


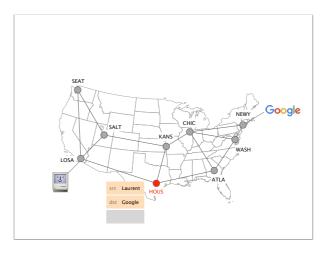






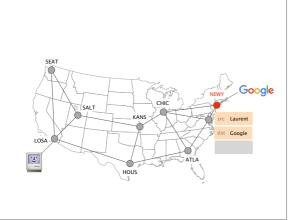


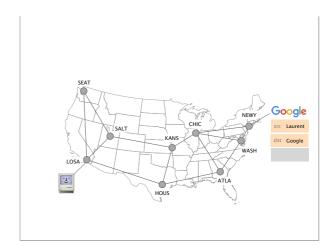




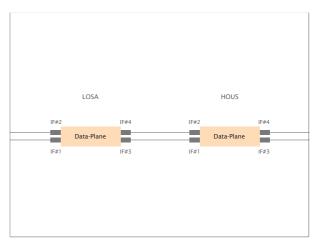


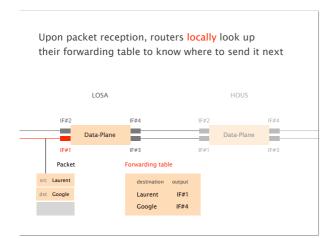


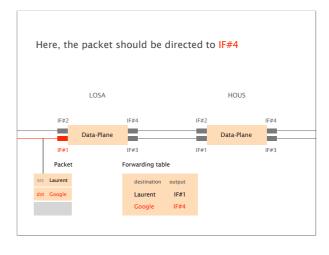


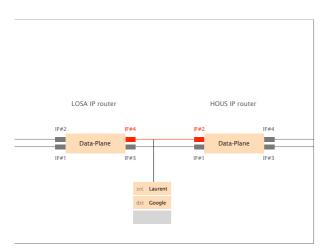


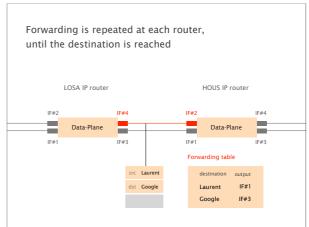


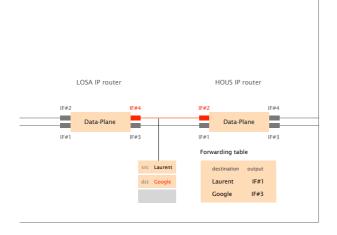


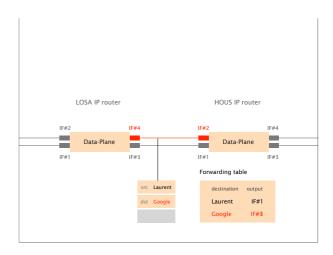


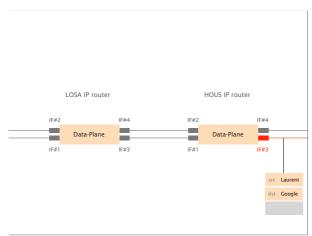


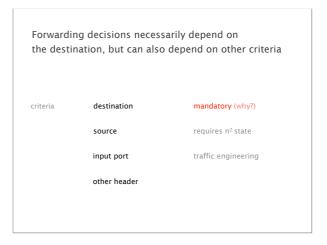




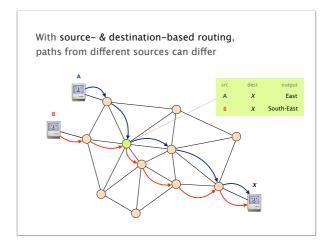


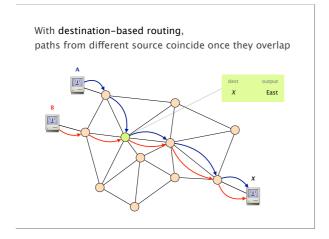






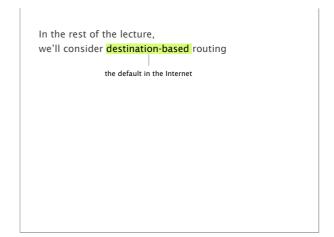


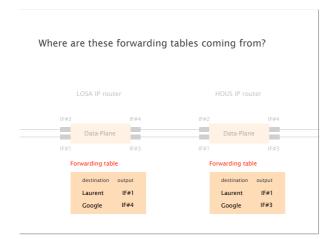


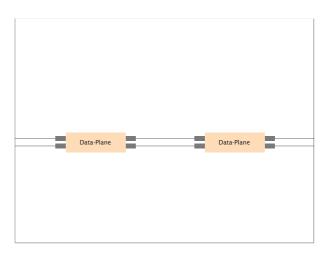


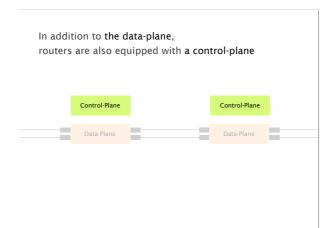


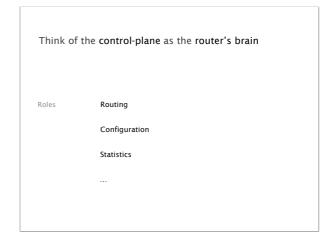
Here is an example of a spanning tree for destination *X*

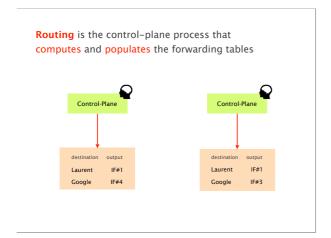


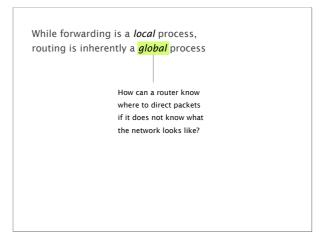




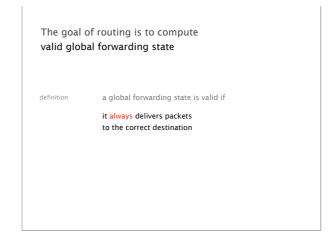


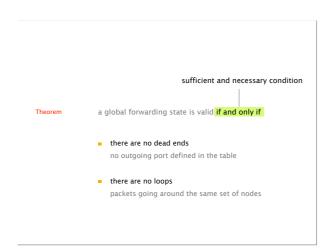


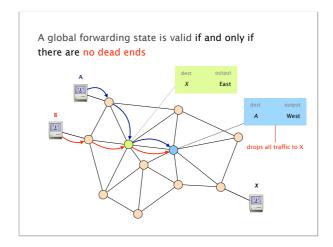


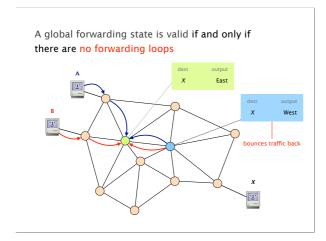


Forwarding vs Routing summary forwarding directing packet to computing the paths an outgoing link packets will follow network-wide scope local hardware software usually always nanoseconds 10s of ms hopefully











No dead ends and no loops are a sufficient and necessary condition for forwarding validity

statement 1

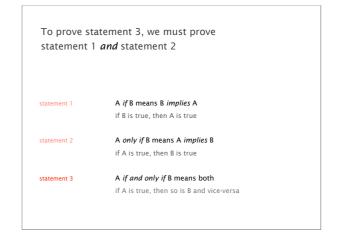
A if B means B implies A if B is true, then A is true

statement 2

A only if B means A implies B if A is true, then B is true

statement 3

A if and only if B means both if A is true, then so is B and vice-versa



Proving the necessary condition is easy

Theorem If a routing state is valid

then there are no loops or dead-end

Proof If you run into a dead-end or a loop

you'll never reach the destination

so the state cannot be correct (contradiction)

Proving the sufficient condition is more subtle Theorem If a routing state has no dead end and no loop then it is valid Proof There is only a finite number of ports to visit A packet can never enter a switch via the same port, otherwise it is a loop (which does not exist by assumption) As such, the packet must eventually reach the destination

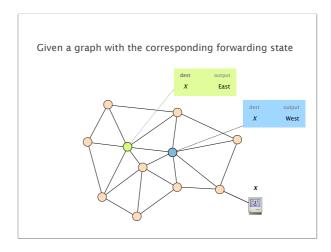
question 1 How do we verify that a forwarding state is valid?

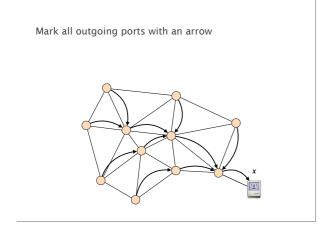
question 2 How do we compute valid forwarding state?

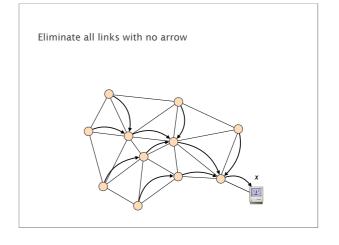
question 1 How do we verify that a forwarding state is valid?

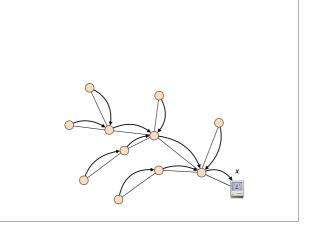
How do we compute valid forwarding state?

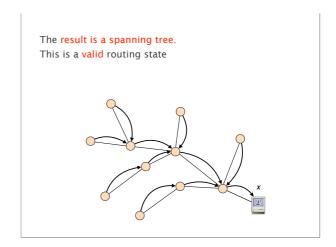
Verifying that a routing state is valid is easy simple algorithm for one destination Mark all outgoing port with an arrow Eliminate all links with no arrow State is valid iff the remaining graph is a spanning-tree

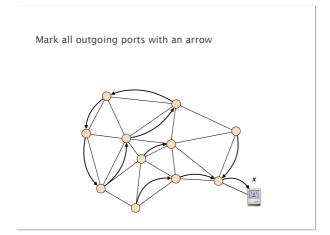


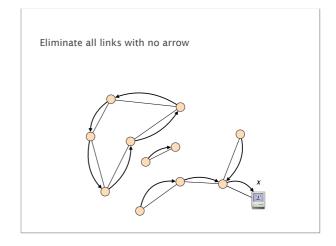


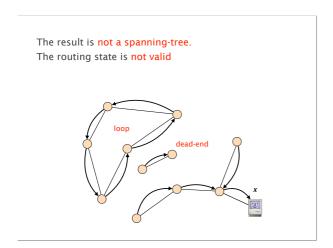


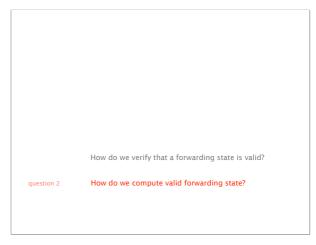


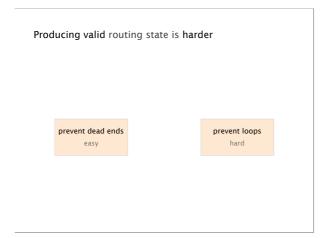


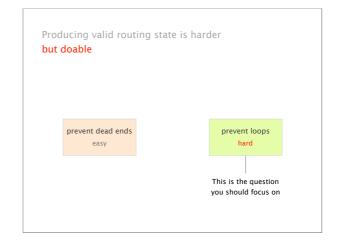












Most routing protocols out there differ in how they avoid loops

> prevent loops hard

Before I give you all the answers it's your turn ...to figure out a way to route traffic in a network

instructions given in class

Essentially, there are three ways to compute valid routing state

	Intuition	Example
#1	Use tree-like topologies	Spanning-tree
#2	Rely on a global network view	Link-State SDN
#3	Rely on distributed computation	Distance-Vector

Essentia there are	lly, e three ways to compute valid r	outing state
#1	Use tree-like topologies	Spanning-tree
	Rely on a global network view	Link-State SDN
	Rely on distributed computation	Distance-Vector

The easiest way to avoid loops is to use a topology where loops are impossible

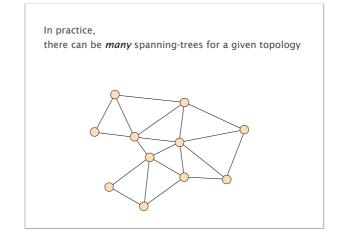
simple algorithm Take an arbitrary topology Build a spanning tree and

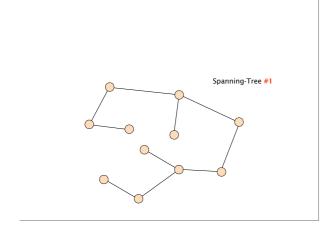
Done!

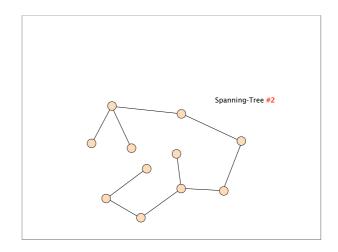
ignore all other links

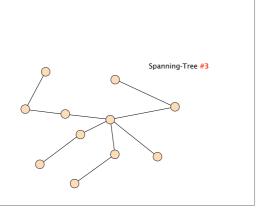
Why does it work?

Spanning-trees have only one path between any two nodes







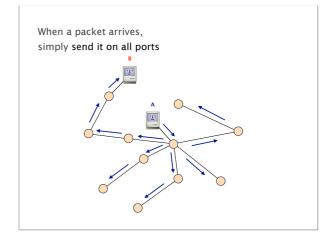


We'll see how to compute a spanning-tree in two weeks. For now, assume it is possible

Once we have a spanning tree,

forwarding on it is easy

literally just flood
the packets everywhere



While flooding works, it is quite wasteful

Luckily, nodes can learn how to reach nodes by remembering where packets came from

intuition

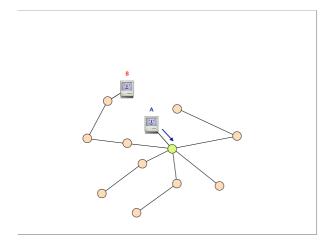
if

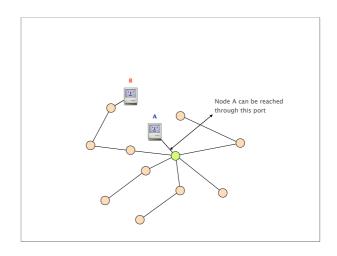
flood packet from node A entered switch X on port 4

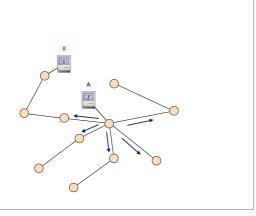
then

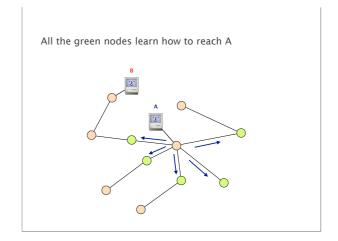
switch X can use port 4

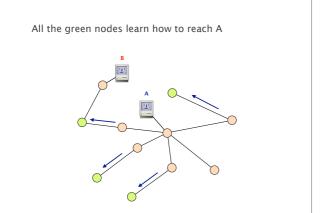
to reach node A

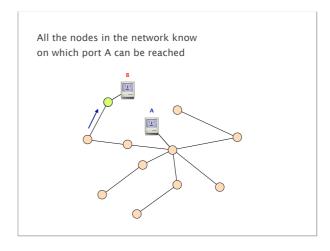


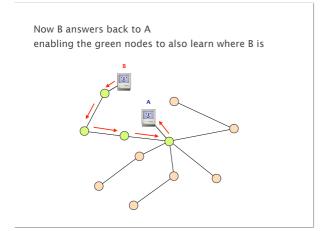


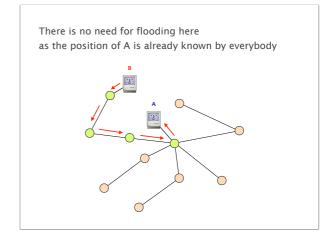


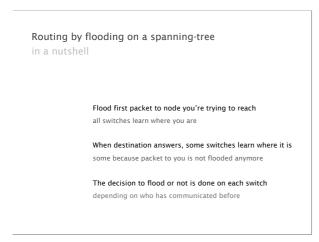


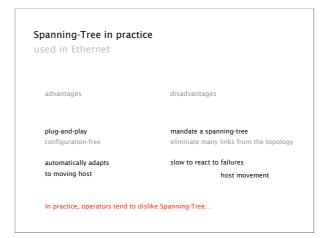












Essentially,

there are three ways to compute valid routing state

Use tree-like topologies

Spanning-tree

#2

Rely on a global network view

SDN

Rely on distributed computation

Distance-Vector

BGP

If each router knows the entire graph, then it is easy to find paths to any given destination

Once a node u knows the entire topology, it can compute shortest-paths using Dijkstra's algorithm

Initialization

Loop

 $S = \{u\}$ for all nodes v: while not all nodes in S:

if (v is adjacent to u): D(v) = c(u,v) add w with the smallest D(w) to S update D(v) for all adjacent v not in S: $D(v) = \min\{D(v), D(w) + c(w,v)\}$

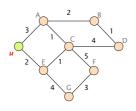
else:

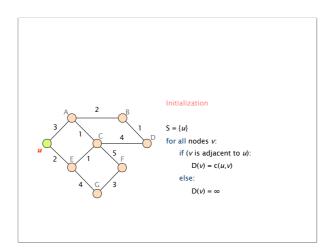
 $\mathsf{D}(v) = \infty$

u is the node running the algorithm $S = \{u\}$ for all nodes v:

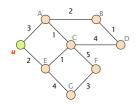
if (v is adjacent to u): $D(v) = \frac{c(u,v)}{c(u,v)} - \frac{c(u,v)}{c(u,v)}$ is the weight of the link else: connecting u and v $D(v) = \infty$ $D(v) = \infty$ D(v) is the smallest distance currently known by u to reach v

Let's compute the shortest-paths from u



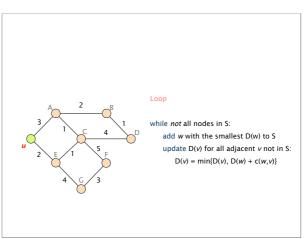


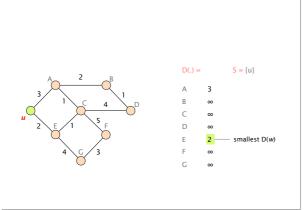
D is initialized based on u's weight, and S only contains u itself

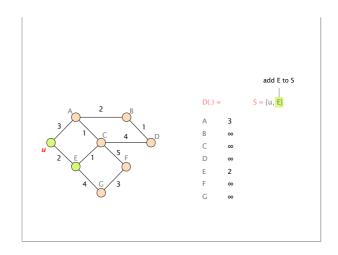


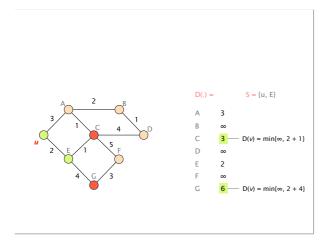
D(.) = S = {u}

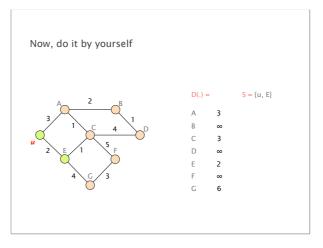
A 3
B \infty
C \infty
D \infty
E 2
F \infty
G \infty

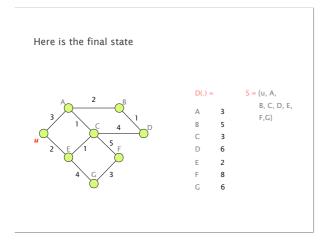


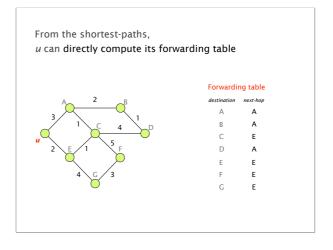


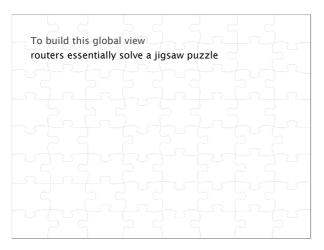


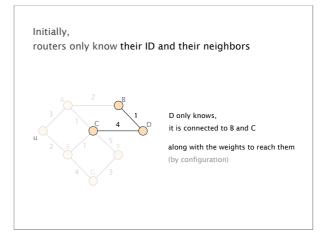




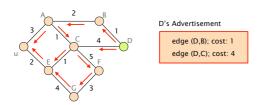








Each routers builds a message (known as Link-State) and floods it (reliably) in the entire network



At the end of the flooding process, everybody share the exact same view of the network required for correctness see exercise

We'll see in few weeks how OSPF implements all this in real networks (and is used within ETH's)

Essentially,
there are three ways to compute valid routing state

Use tree-like topologies Spanning-tree

Rely on a global network view Link-State
SDN

#3 Rely on distributed computation Distance-Vector
BGP

Instead of locally compute paths based on the graph, paths can be computed in a distributed fashion

Let d.(y) be the cost of the least-cost path known by x to reach y

Let $d_x(y)$ be the cost of the least-cost path known by x to reach y

until convergence

Each node bundles these distances into one message (called a vector) that it repeatedly sends to all its neighbors Let d_x(y) be the cost of the least-cost path known by x to reach y

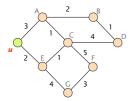
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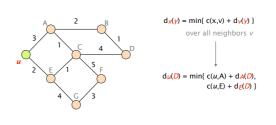
Each node updates its distances based on neighbors' vectors:

d_x(y) = min{ c(x,v) + d_x(y) } over all neighbors v

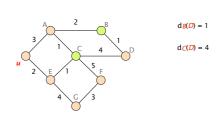
Let's compute the shortest-path from *u* to D



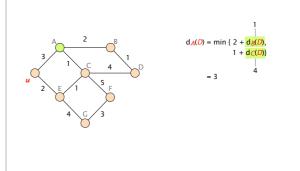
The values computed by a node $\it u$ depends on what it learns from its neighbors (A and E)



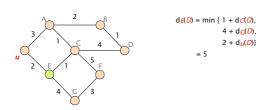
To unfold the recursion, let's start with the direct neighbor of D



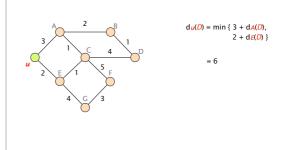
B and C announce their vector to their neighbors, enabling A to compute its shortest-path



As soon as a distance vector changes, each node propagates it to its neighbor



Eventually, the process converges to the shortest-path distance to each destination



As before, *u* can directly infer its forwarding table by directing the traffic to the best neighbor

the one which advertised the smallest cost

In few weeks, we'll learn how BGP uses distributed computation to forward packets in the Internet